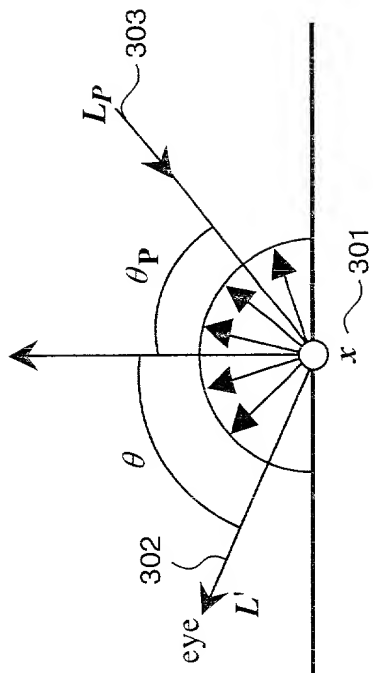
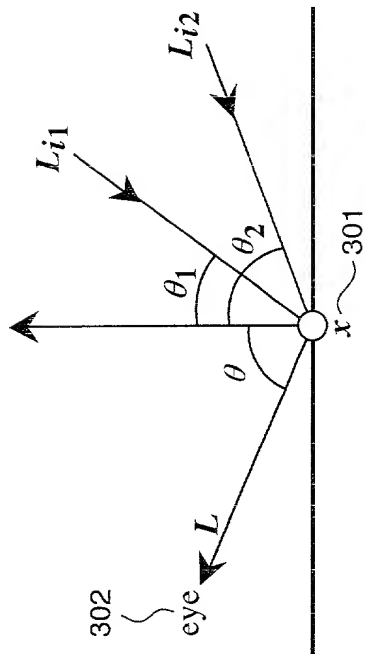


FIG. 1

```
glMatrixMode( GL_PROJECTION );
glLoadMatrix( intrinsic matrix of projector );
glMultMatrix( xform for rendering view )
glMultMatrix( inverse(xform for shading view) );
glMatrixMode( GL_MODEL VIEW );
glLoadMatrix( xform for shading view );
// set virtual light position(s)
// render graphics model
```

200

FIG. 2



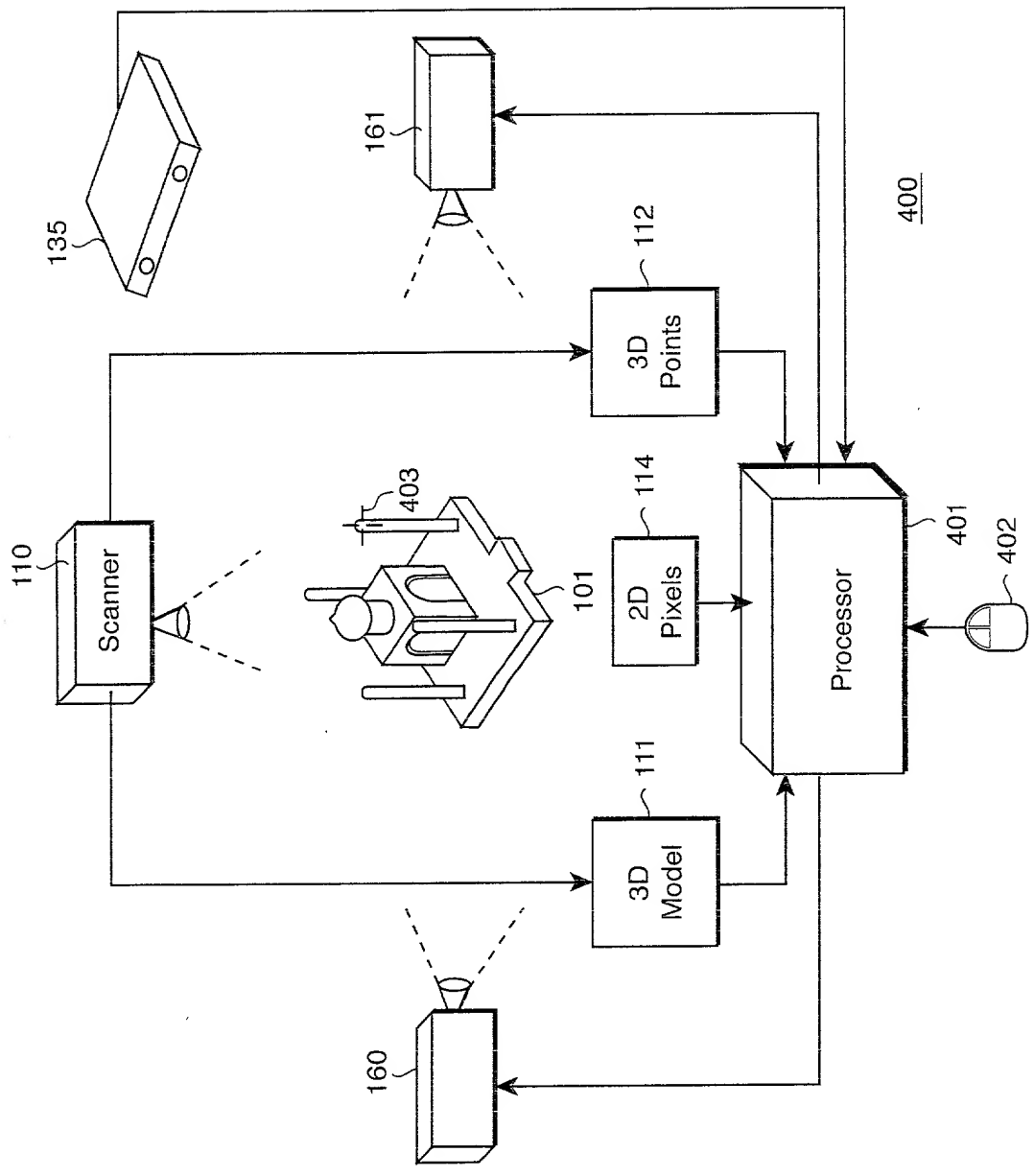


FIG. 4

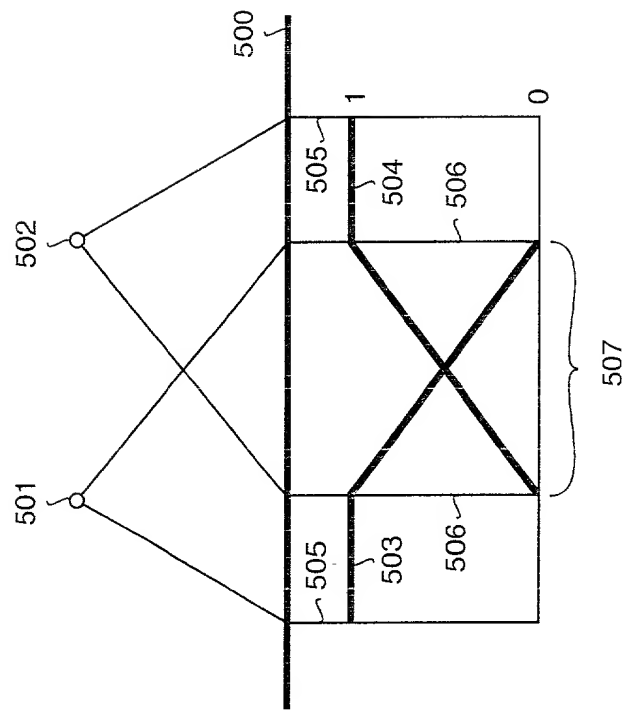


FIG. 5  
PRIOR ART

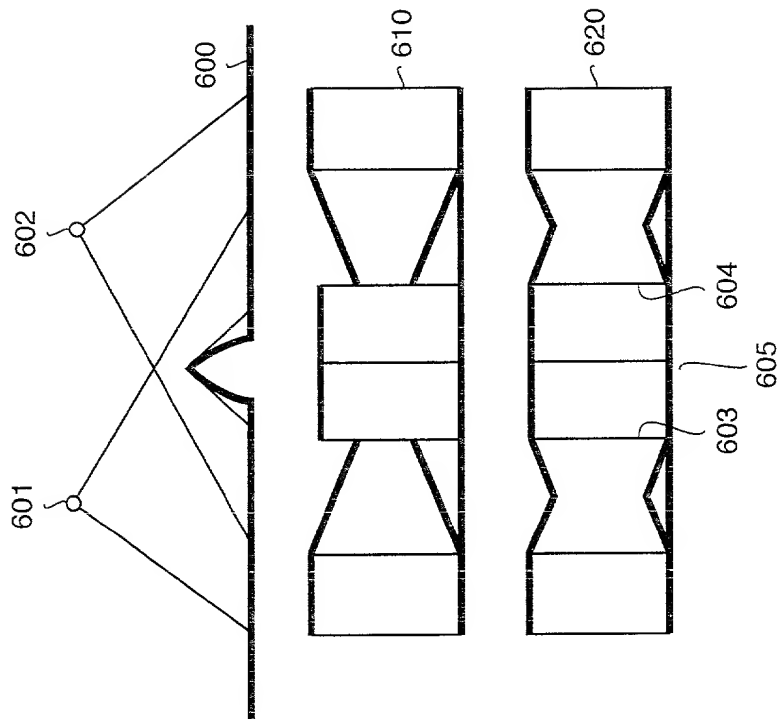


FIG. 6

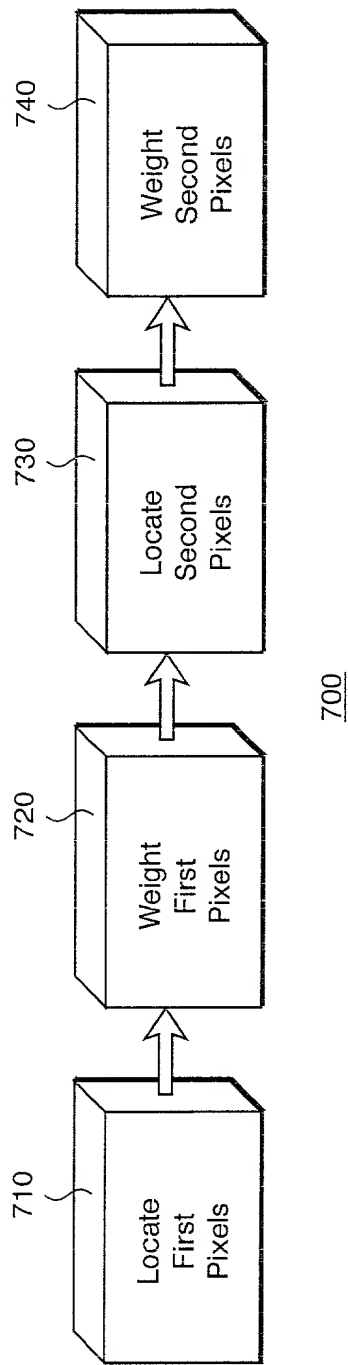


FIG. 7

At each projector,  
    Compute boundaries between regions of overlap count 1 and  $>1$   
    Compute depth discontinuities using edge detection in depth buffer  
    For each pixel in overlap region  
        update shortest distance to overlap count = 1 region ignoring  
        paths crossing depth discontinuity

At each projector,  
    For each pixel in overlap region  
        Find all corresponding pixels in other projectors  
        Assign weights inversely proportional to the shortest distance

800

FIG. 8



